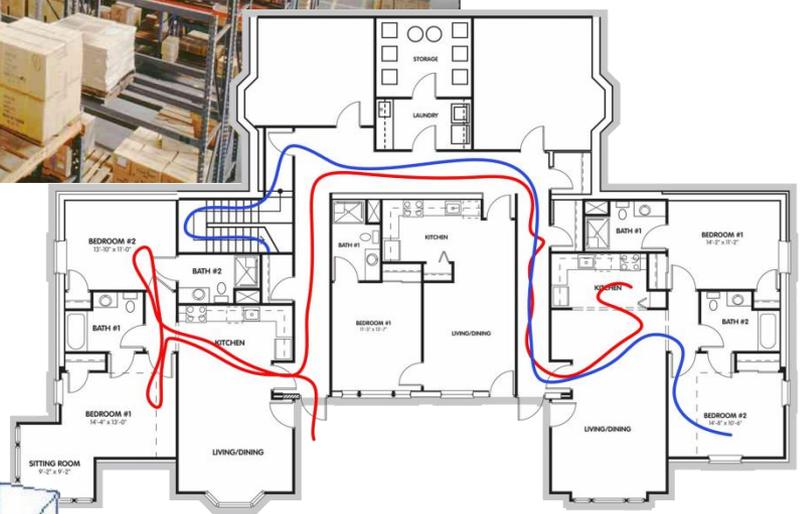
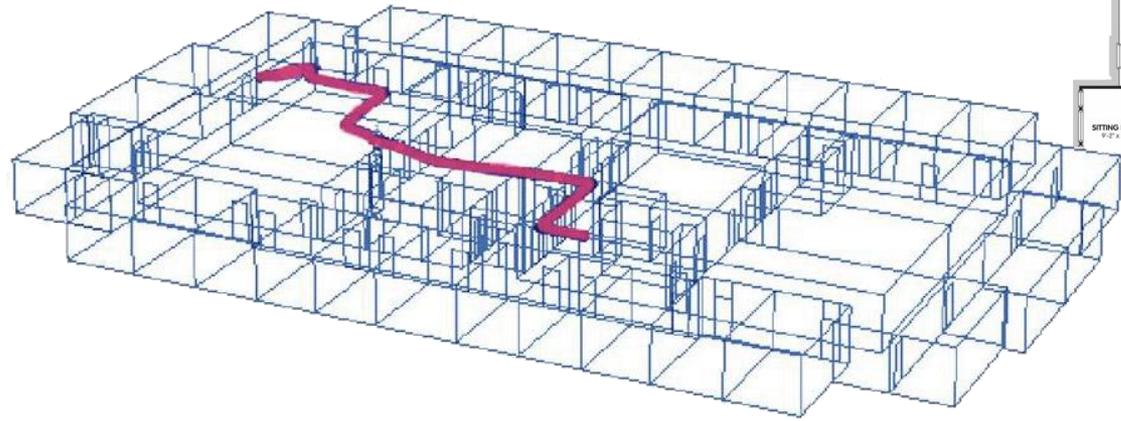
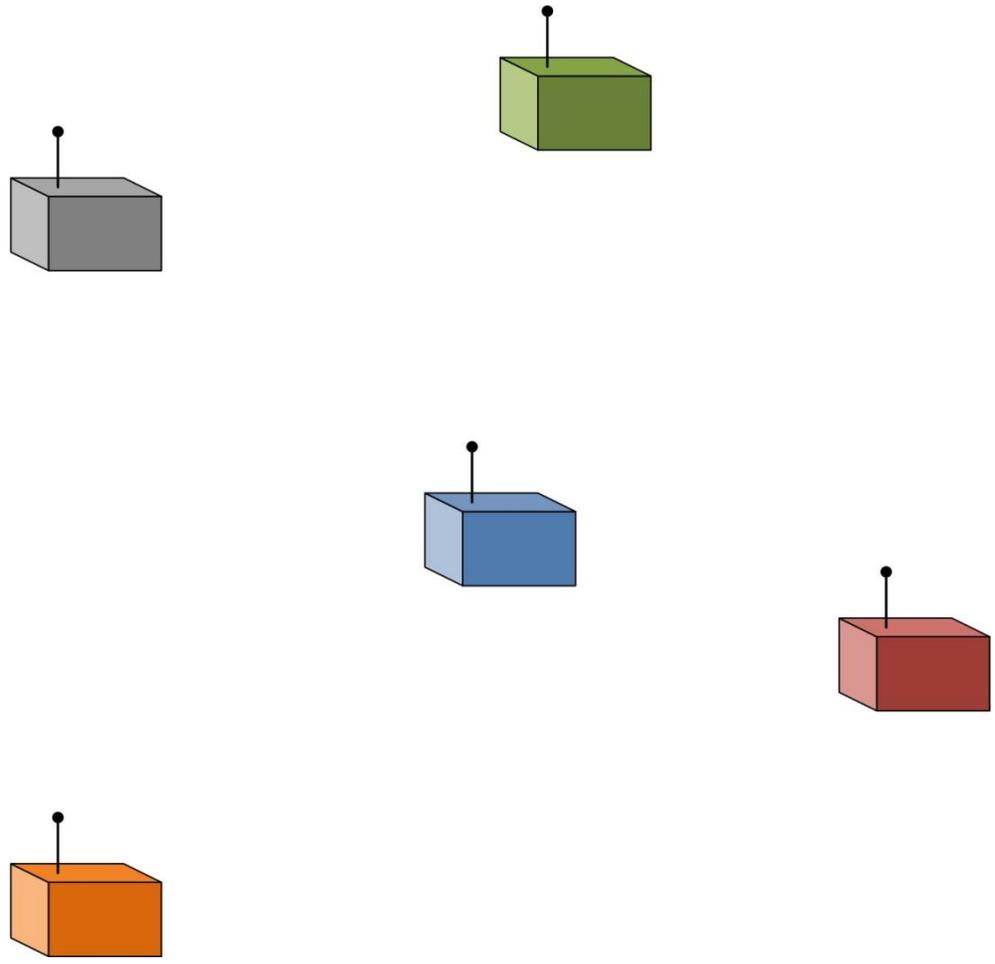


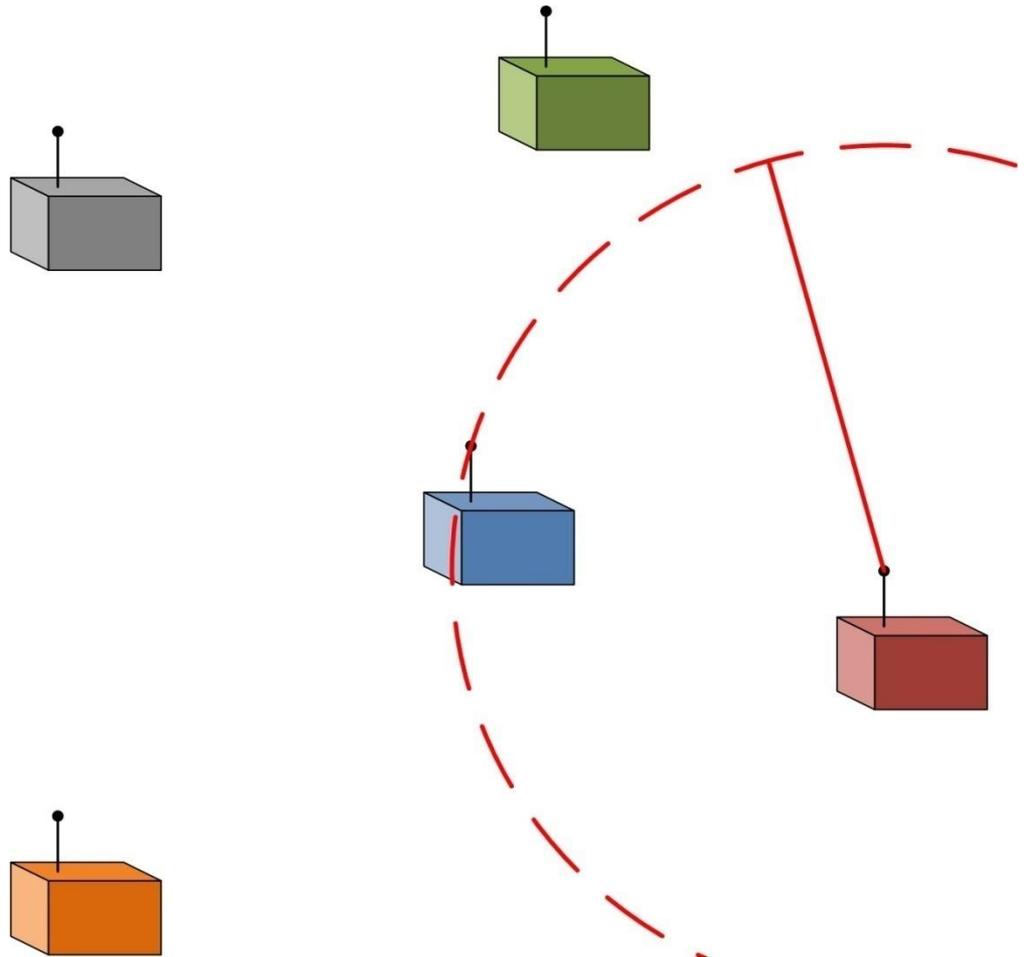
# Location Awareness In Wireless Networks



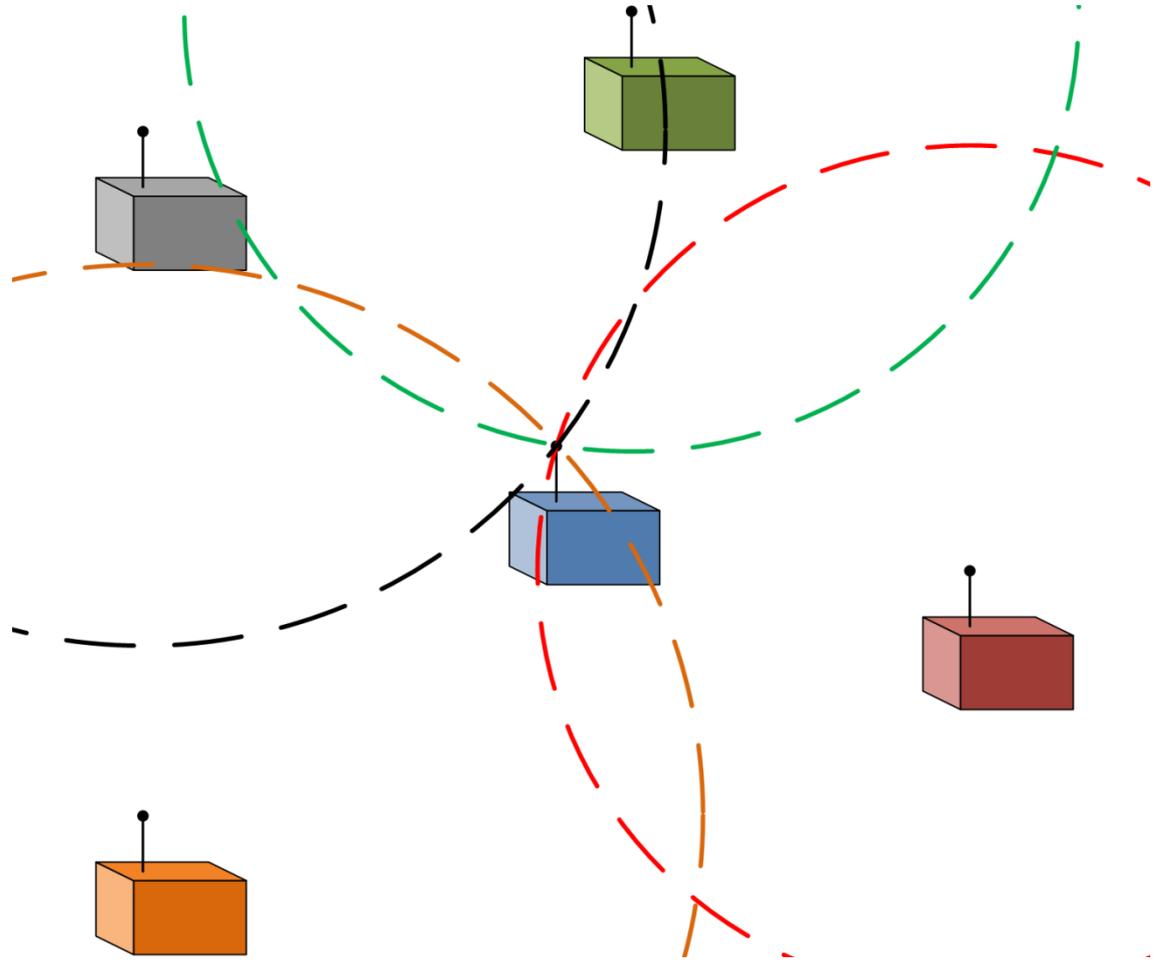
# The Localization Problem



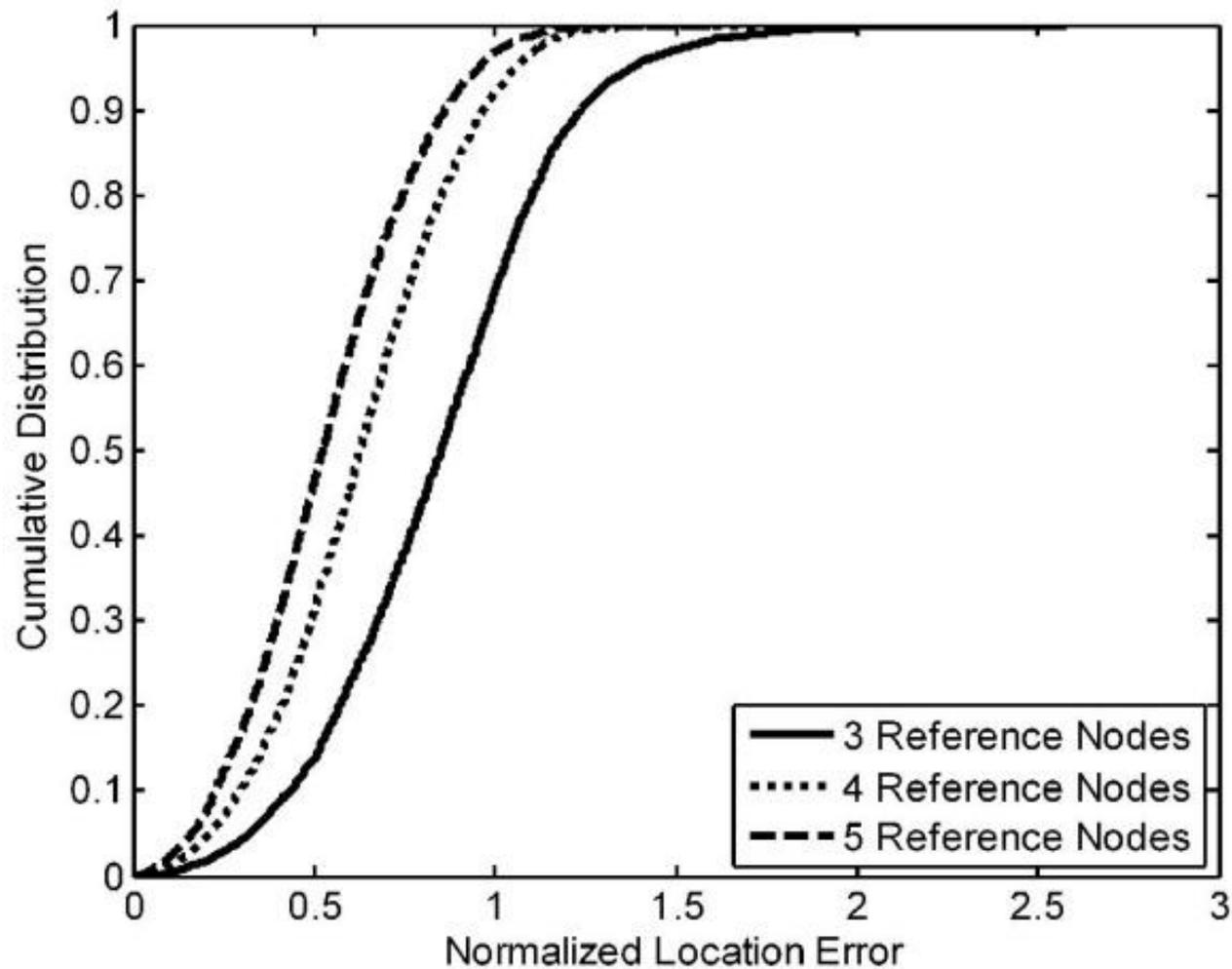
# The Localization Problem



# The Localization Problem



# Location Accuracy vs. Ranging Accuracy



# Ranging Constraints

IEEE 802.15.4 compatible RF time of flight ranging

- 2 MHz RF bandwidth
- Half duplex radios
- 16 channels in 2.4 GHz ISM band
- No time synchronized infrastructure

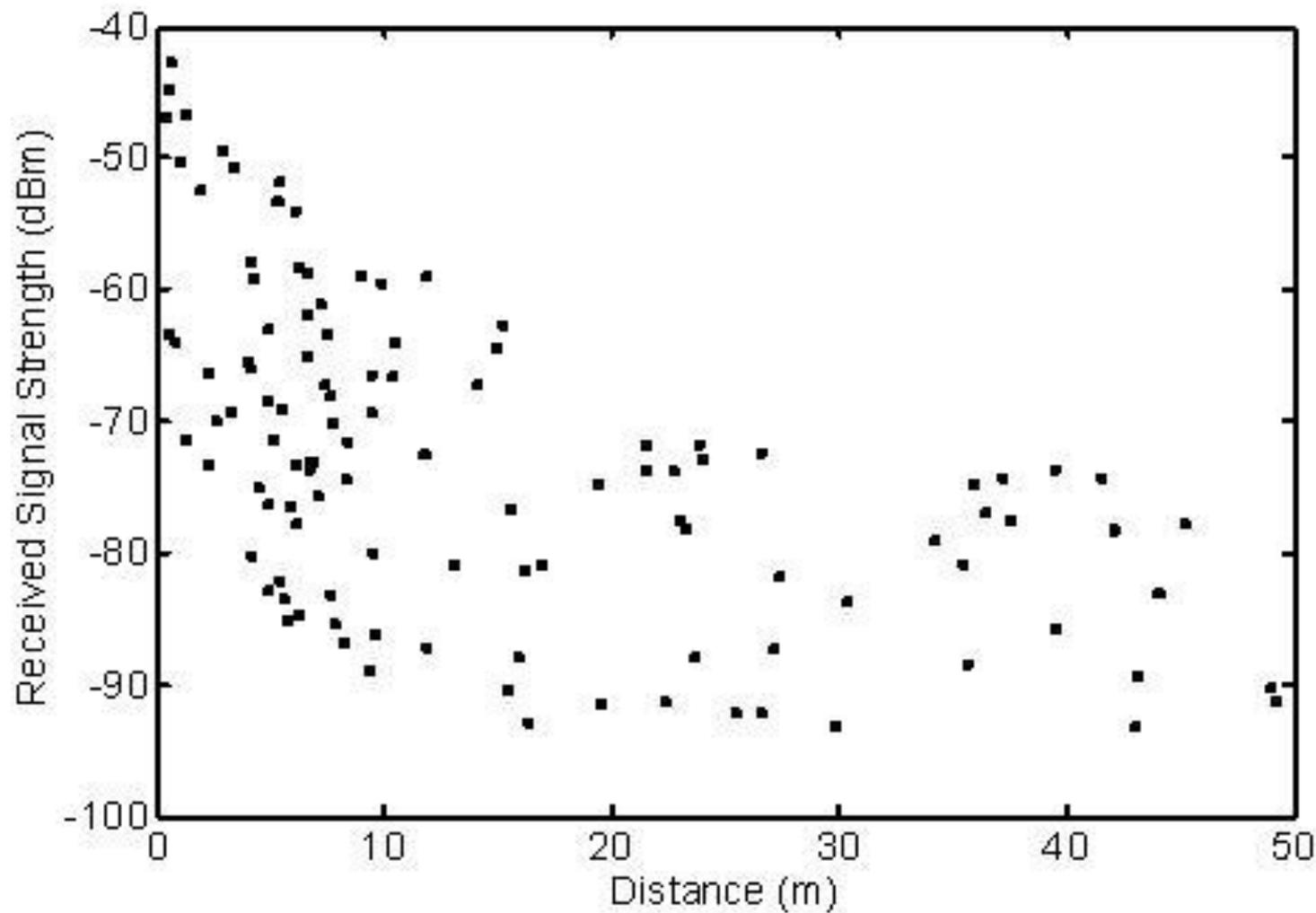
# Why Ranging is Challenging

- Time synchronization
- Noise
- Sampling
- Half duplex radios
- Environmental clutter

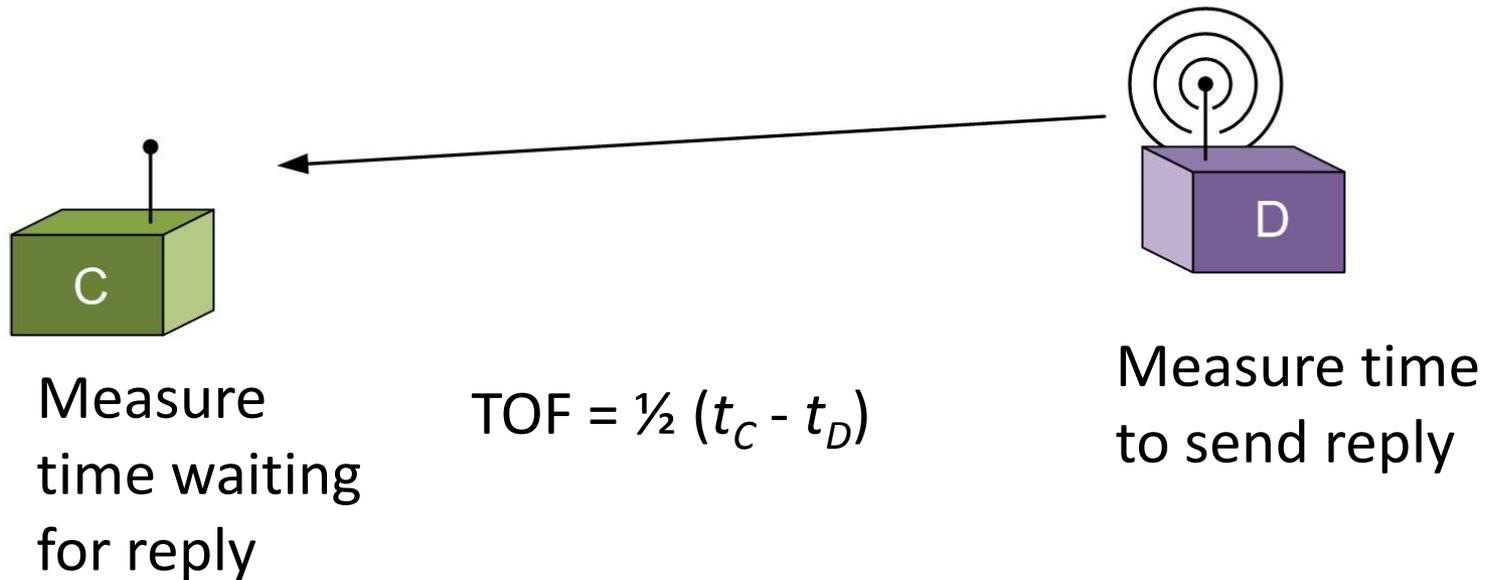
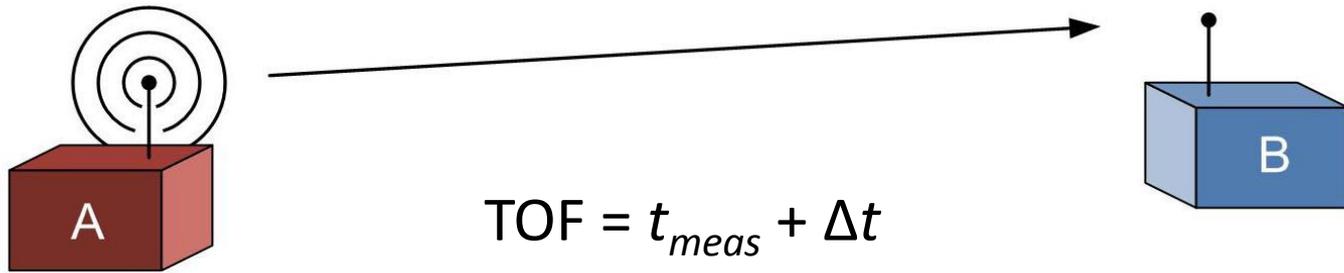
And why do those things matter?

- Speed of light
  - 30 cm/ns
  - 1 ft/ns

# RSS Based Range Estimation

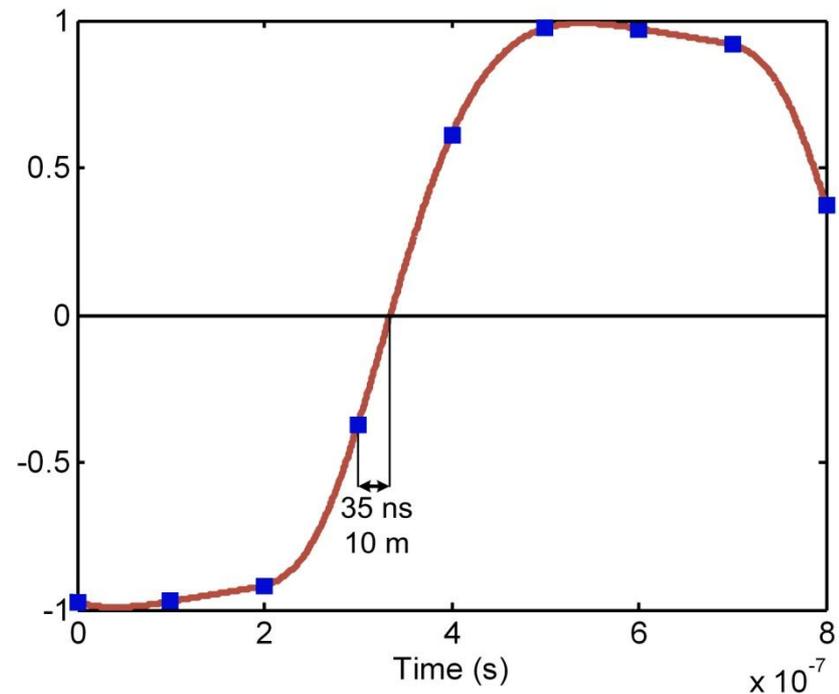


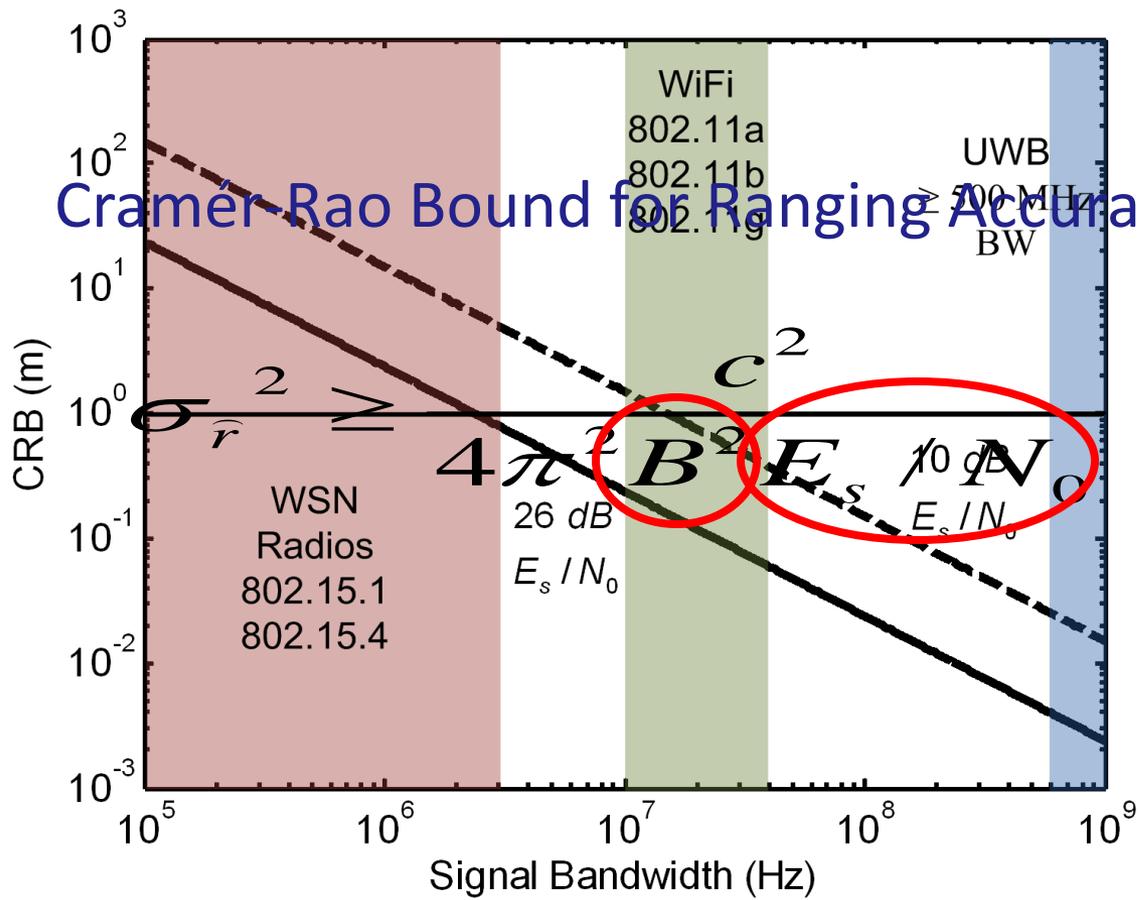
# Time Synchronization



# Range Binning

- Signal sampled by receiver
- Resolution of  $1/f_s$
- What about Nyquist sampling?

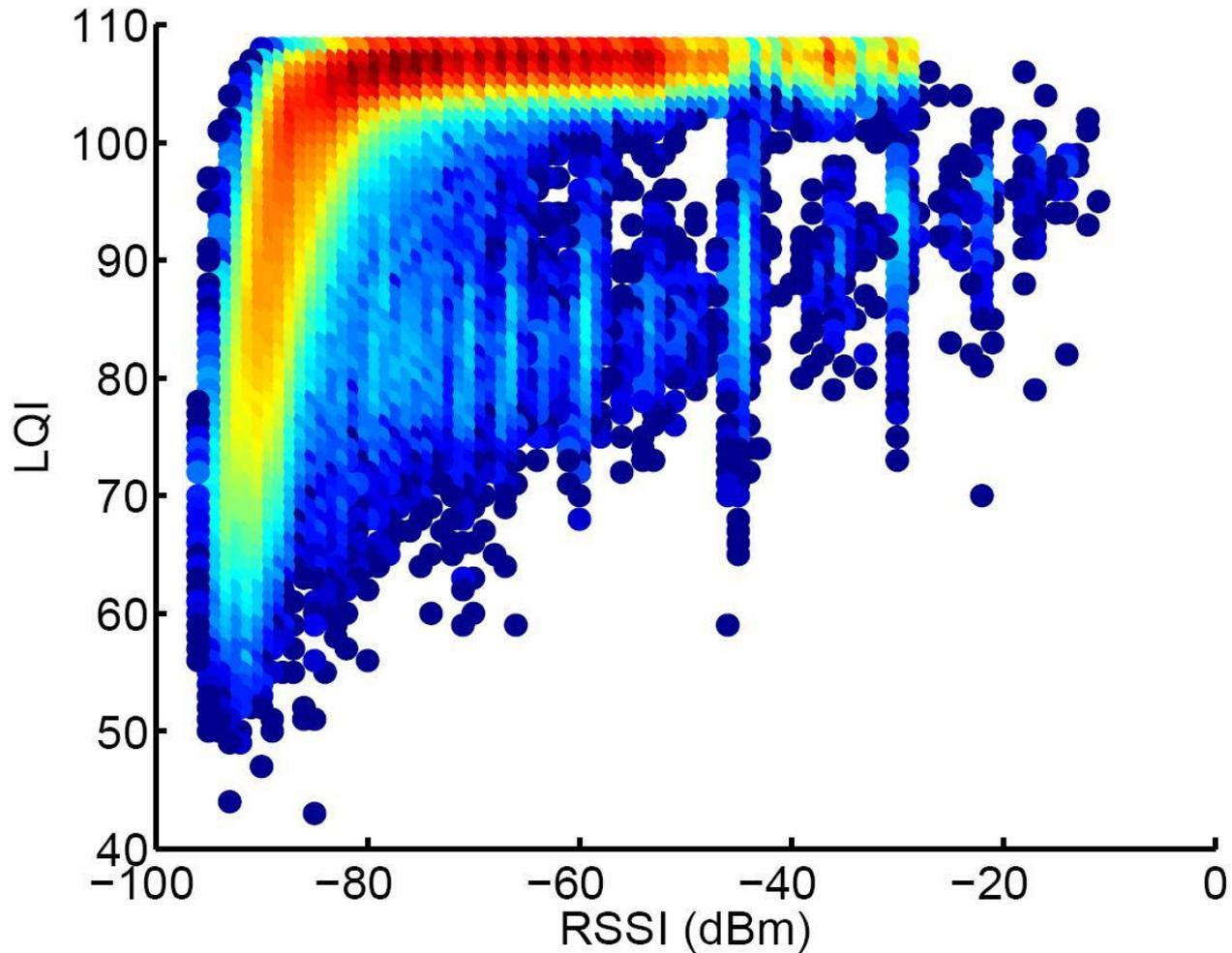




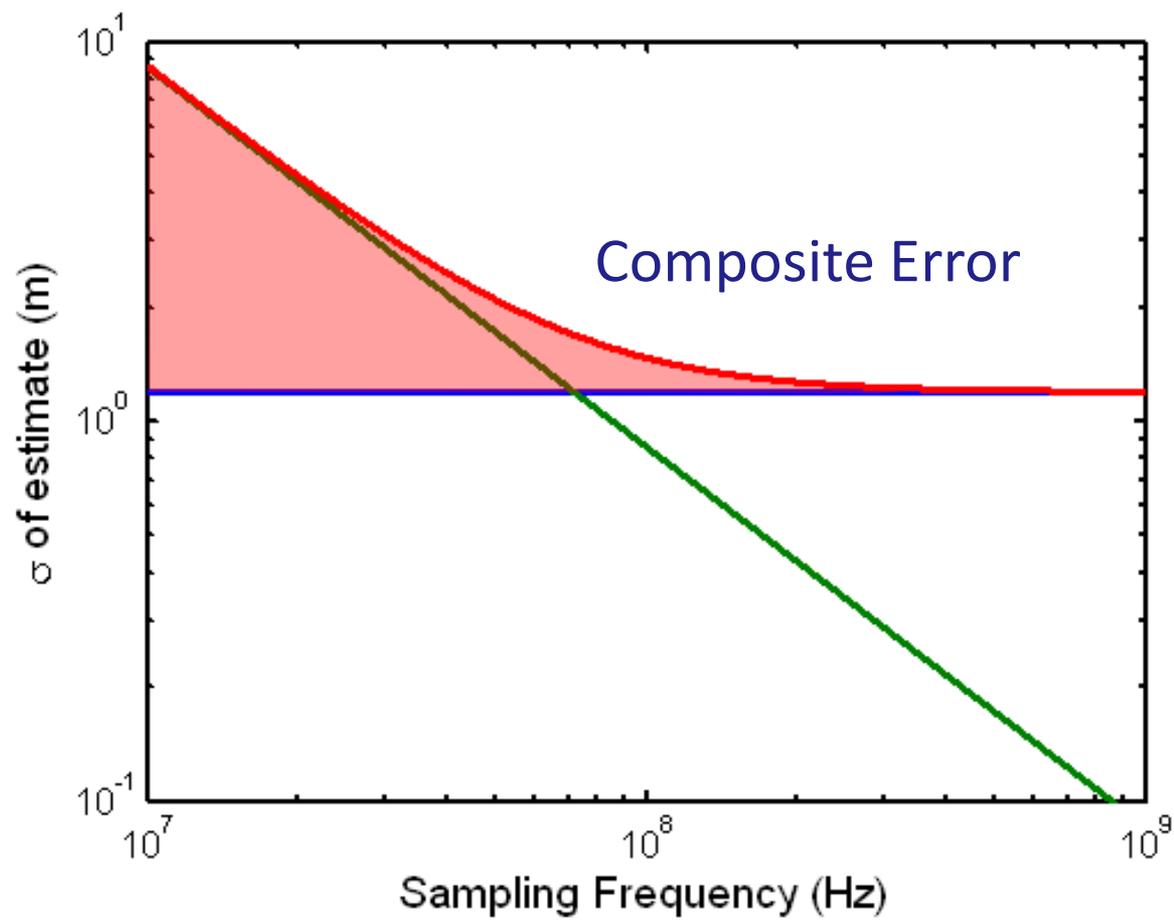
Cramer-Rao Bound for Ranging Accuracy

$$\sigma_{\hat{r}}^2 \geq \frac{c^2}{2\pi^2 B^2 E_s / N_0}$$

# Wireless Sensor Network Conditions



# Range Binning & Noise



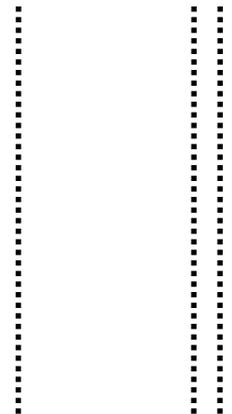
# Full Duplex Two Way Ranging

- Developed during WWII
  - Identify friend or foe
- Widely used in civil aviation starting in 1950's



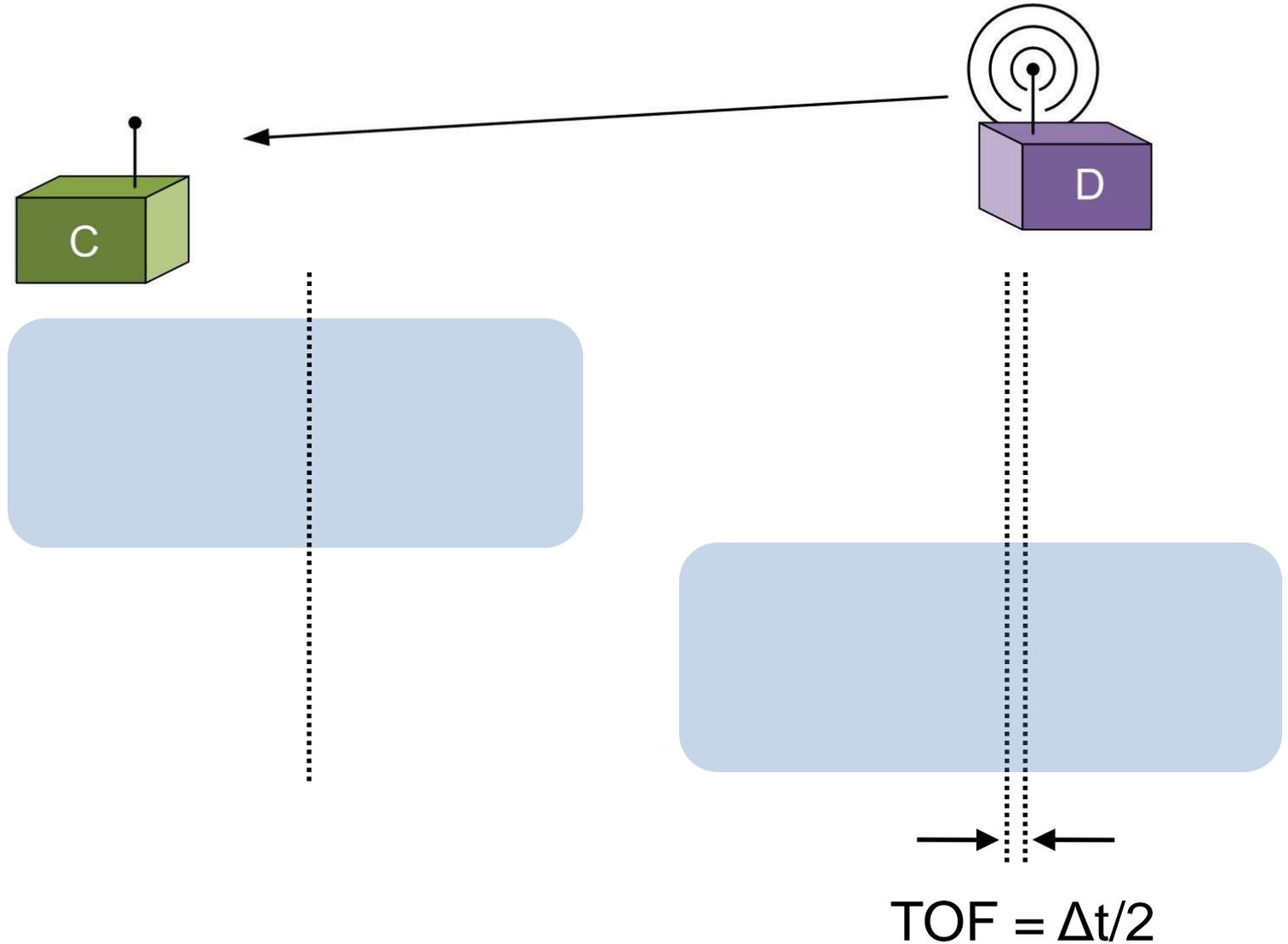
Cessna ARC-RT-359A Transponder  
(Wikipedia)

# Full Duplex Two Way Ranging

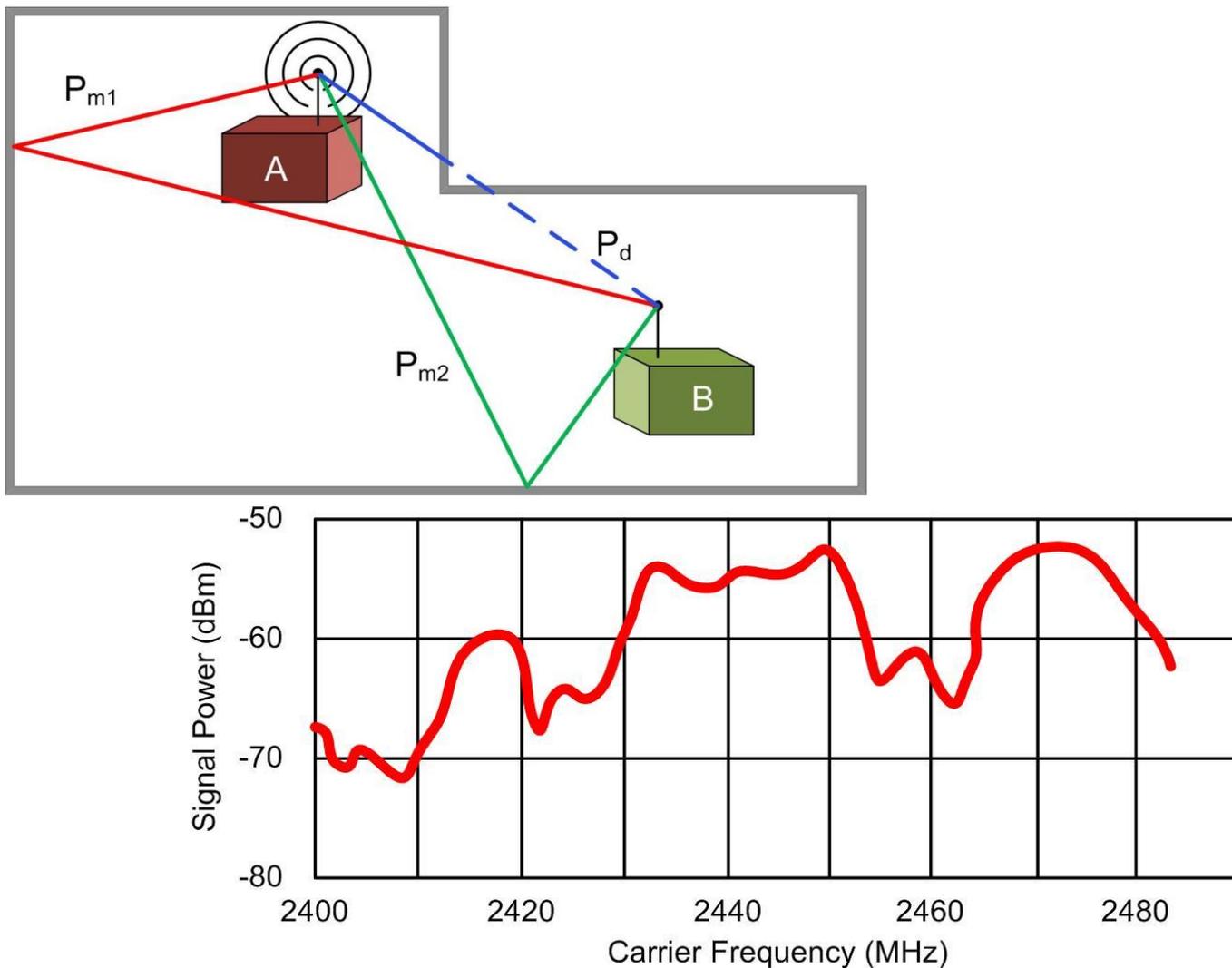


$TOF = \Delta t / 2$

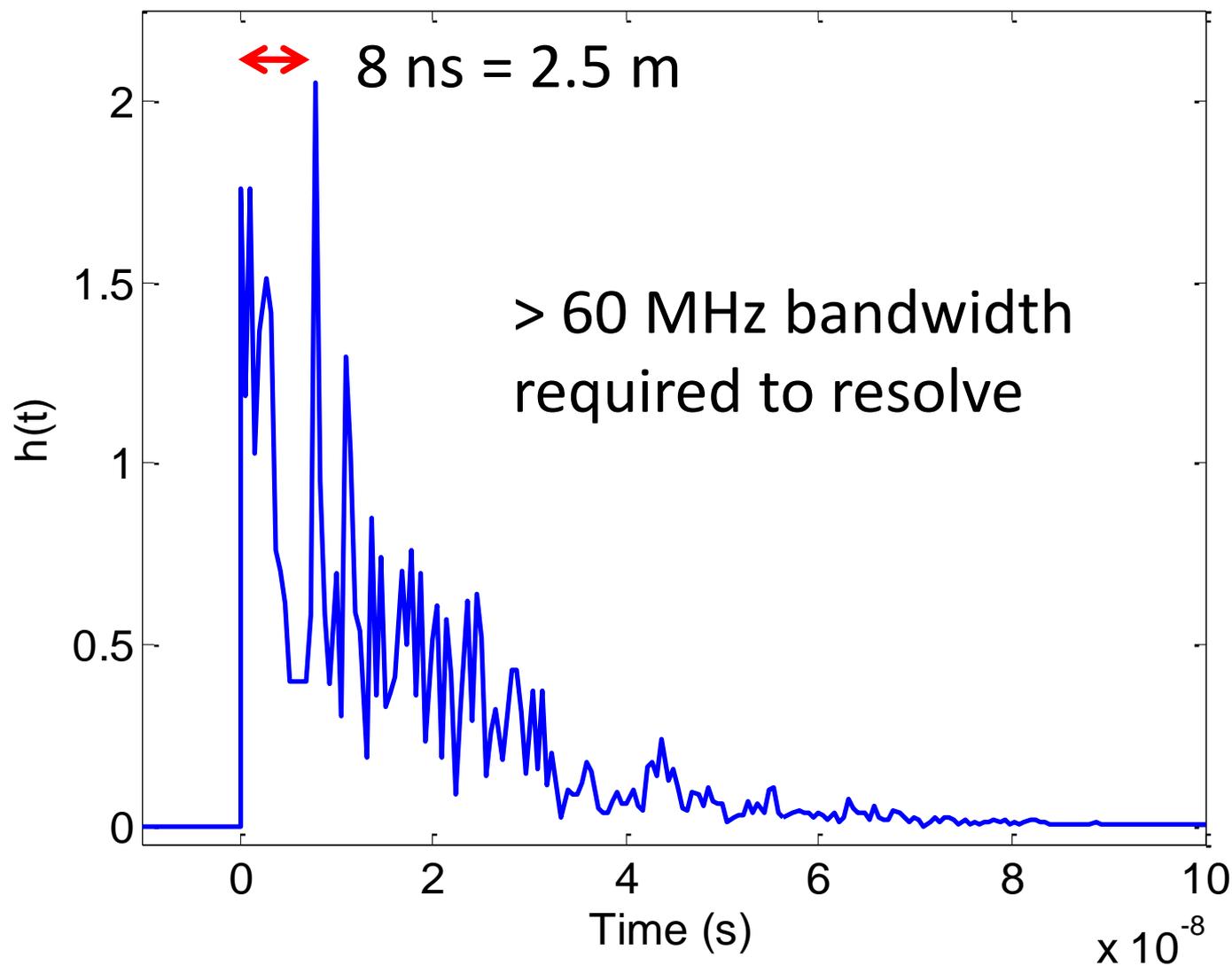
# Code Modulus Synchronization



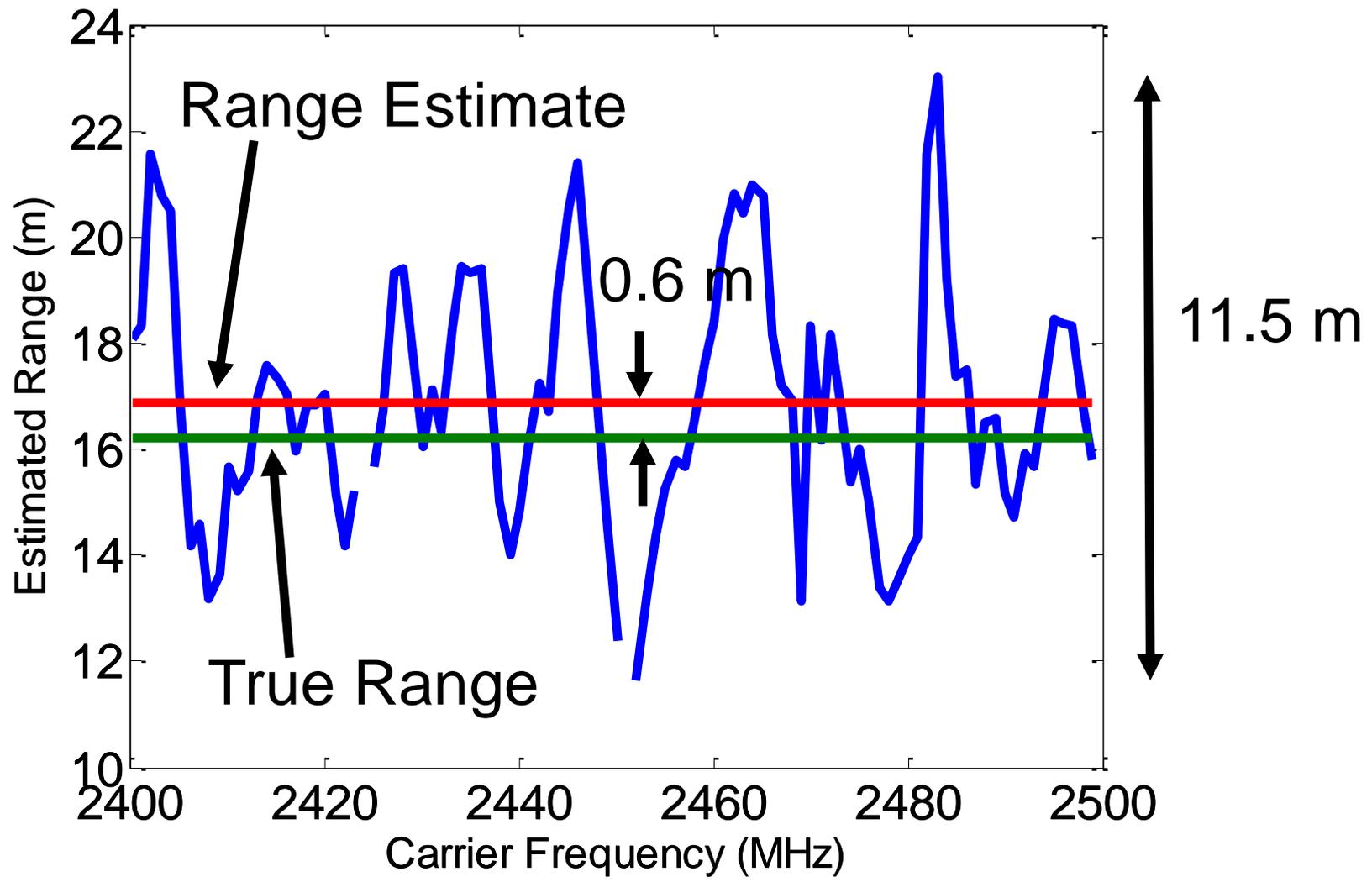
# Multipath Propagation



# Channel Impulse Response



# Dealing With Multipath



# Multipath Mitigation

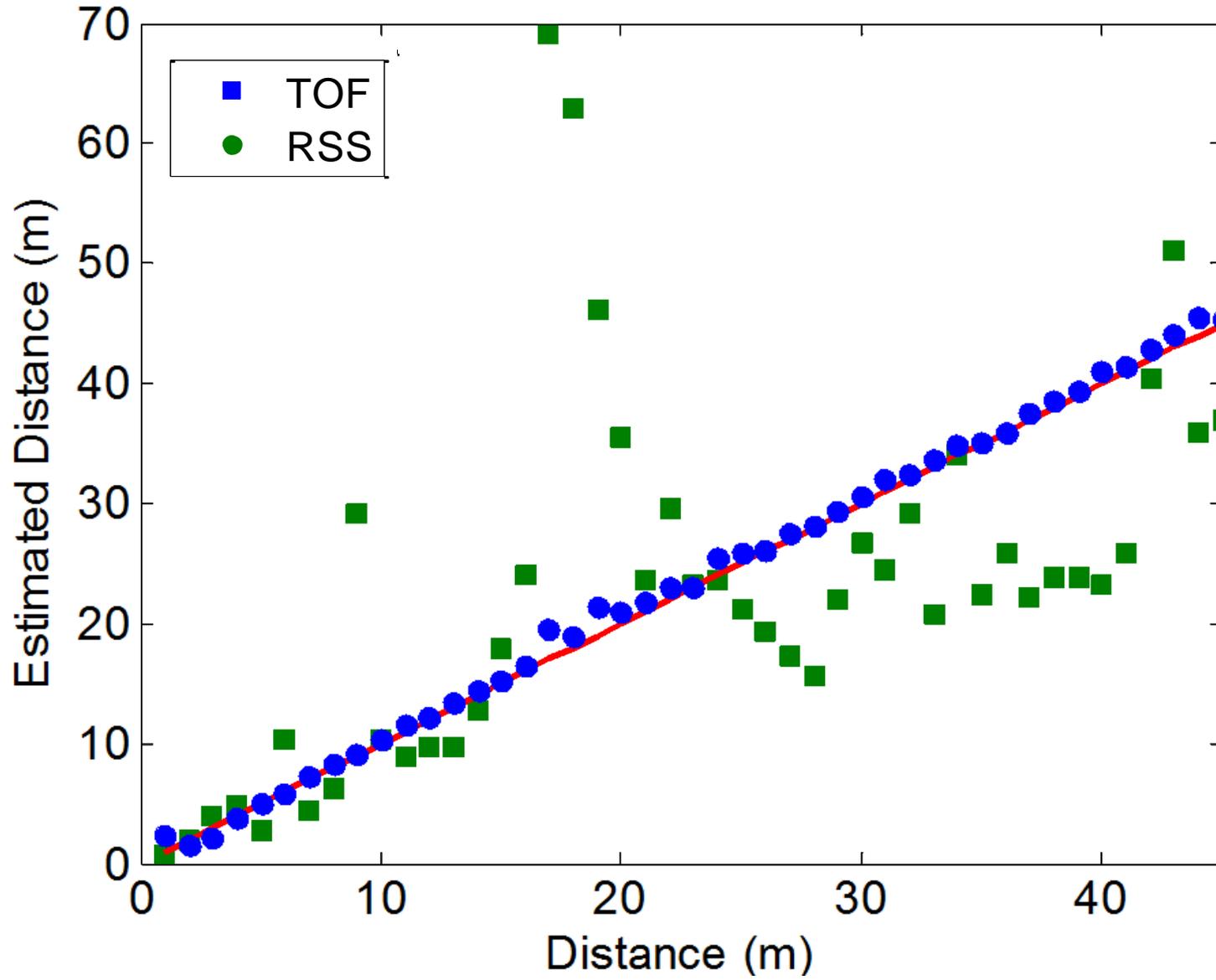
**Proposed method deals well with multipath signals with amplitude less than direct path**

- This is true in all line of sight channels
- It is also true in some obstructed channels

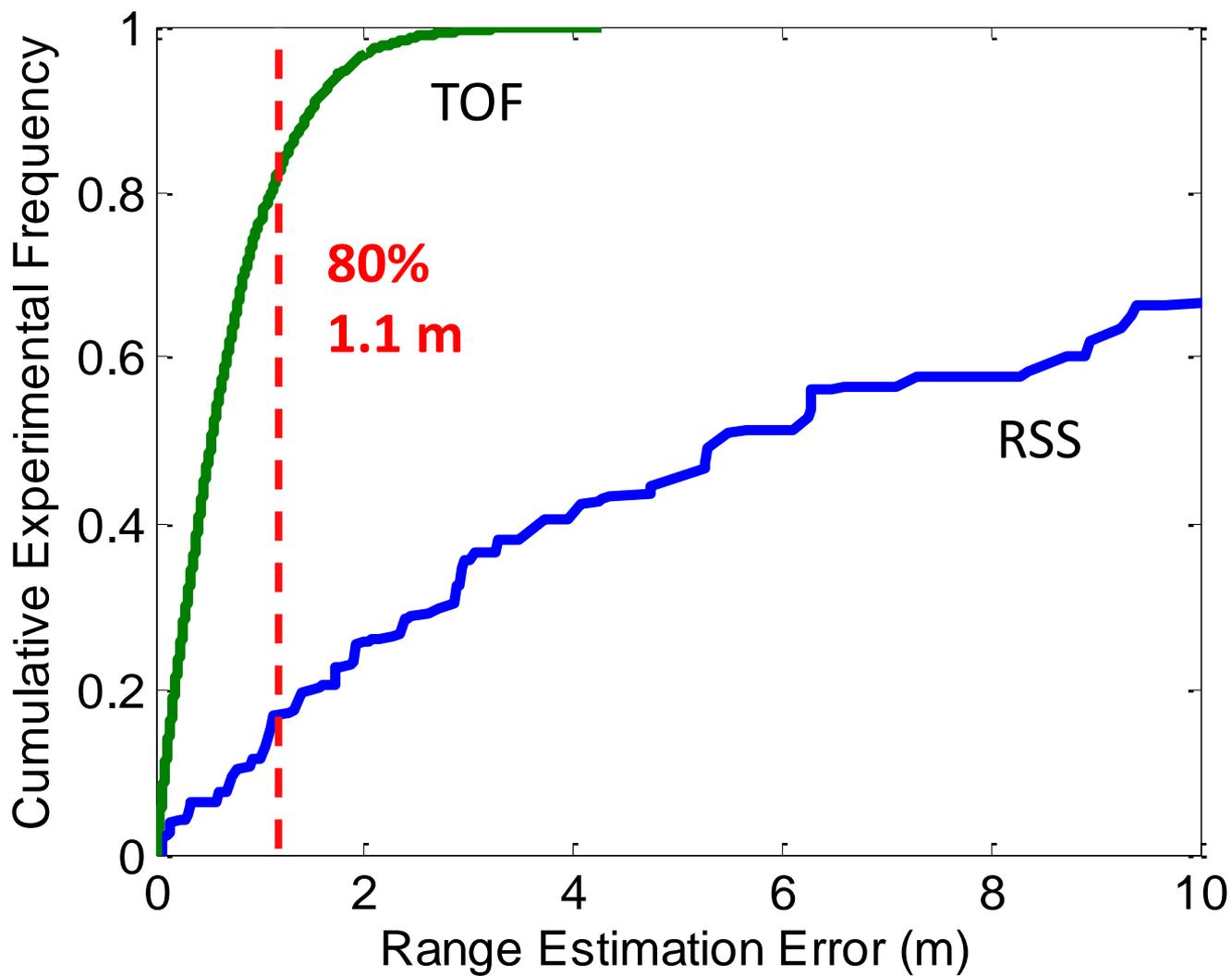
What happens when MP is too strong?

- Large errors result
- Localization algorithm must help mitigate

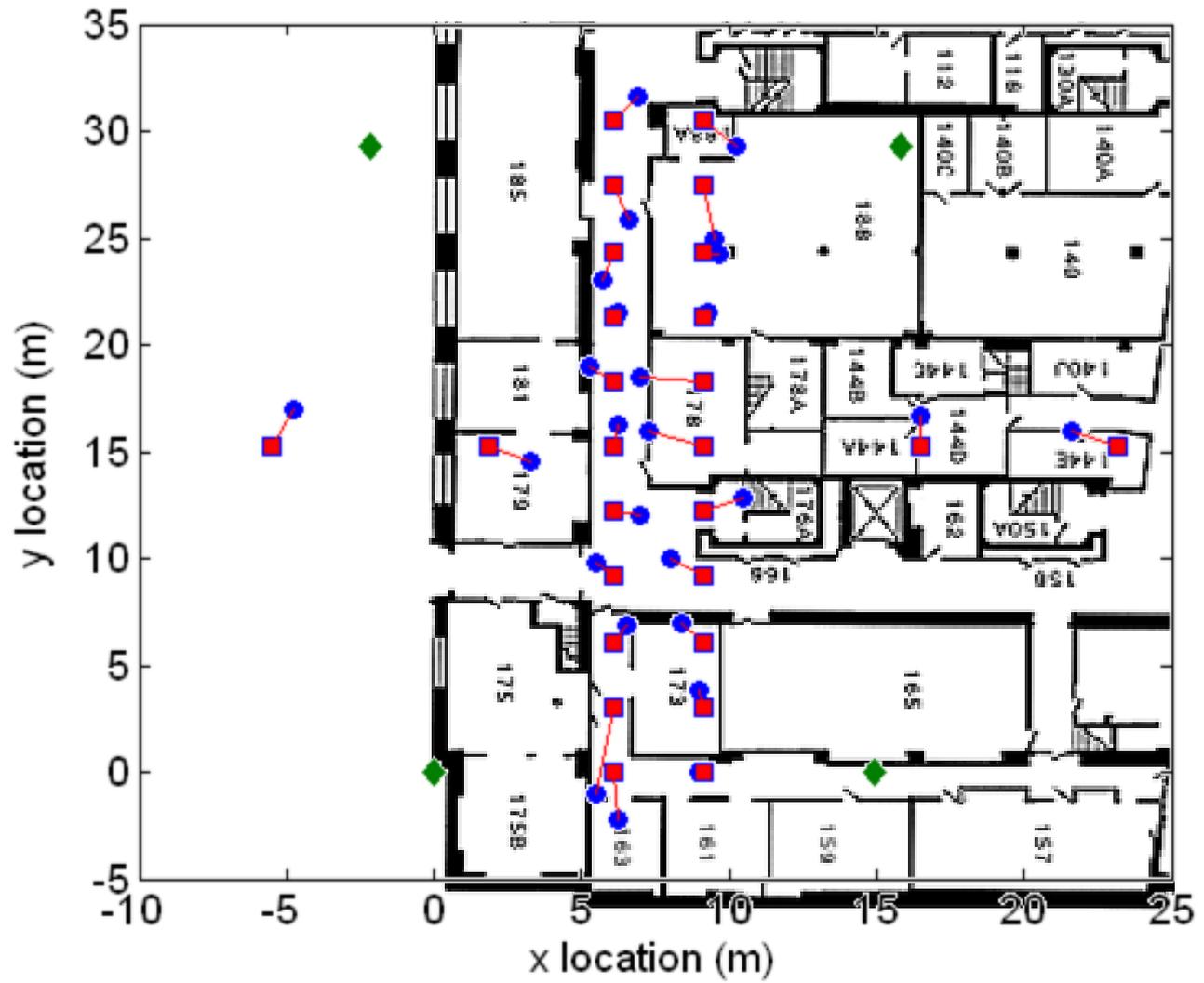
# Comparison to RSS



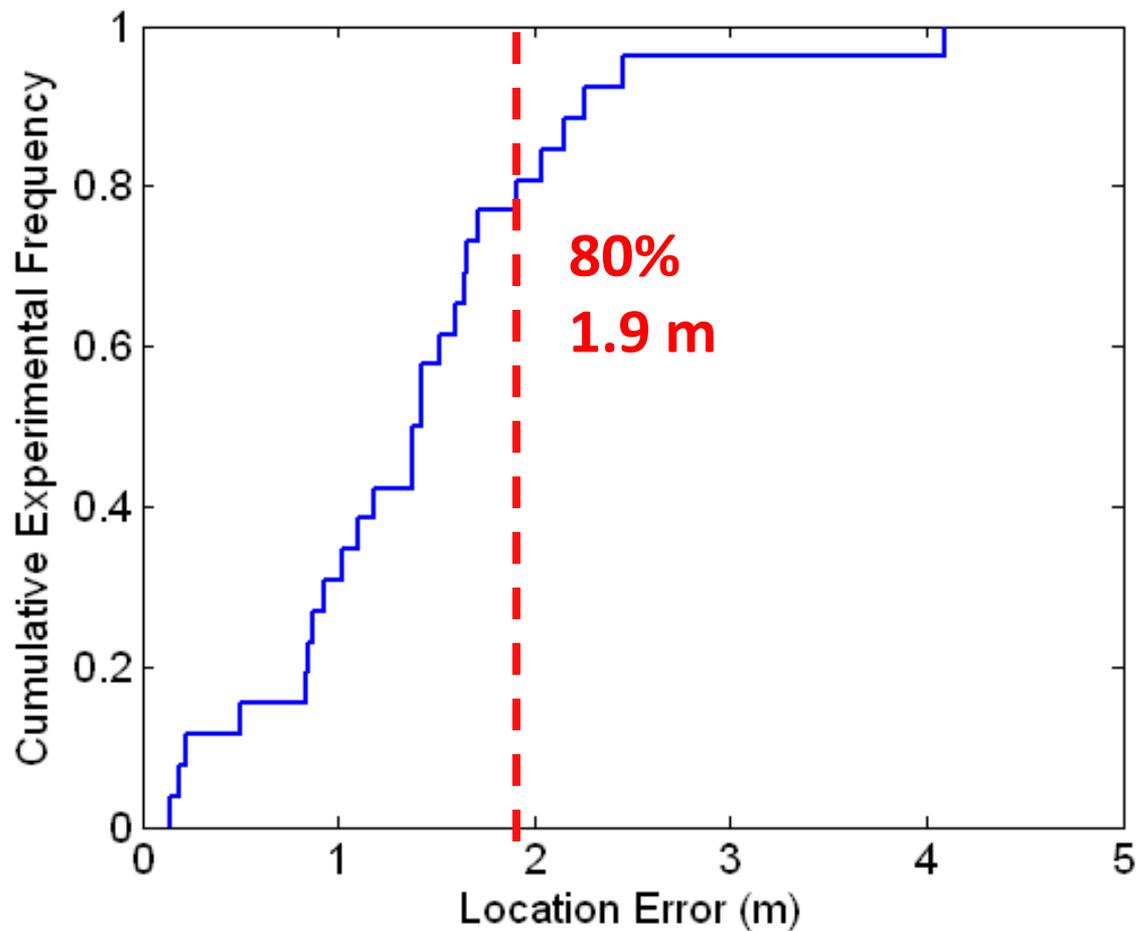
# Outdoor Ranging Accuracy



# Outdoor Location Tracking



# Ranging Accuracy: Indoors



- Fixed node placement is important
- The more fixed nodes the better
- If fixed nodes are above most clutter, results are pretty good.